

qb robotics

fast, flexible technology



CENTRO "E. PIAGGIO"
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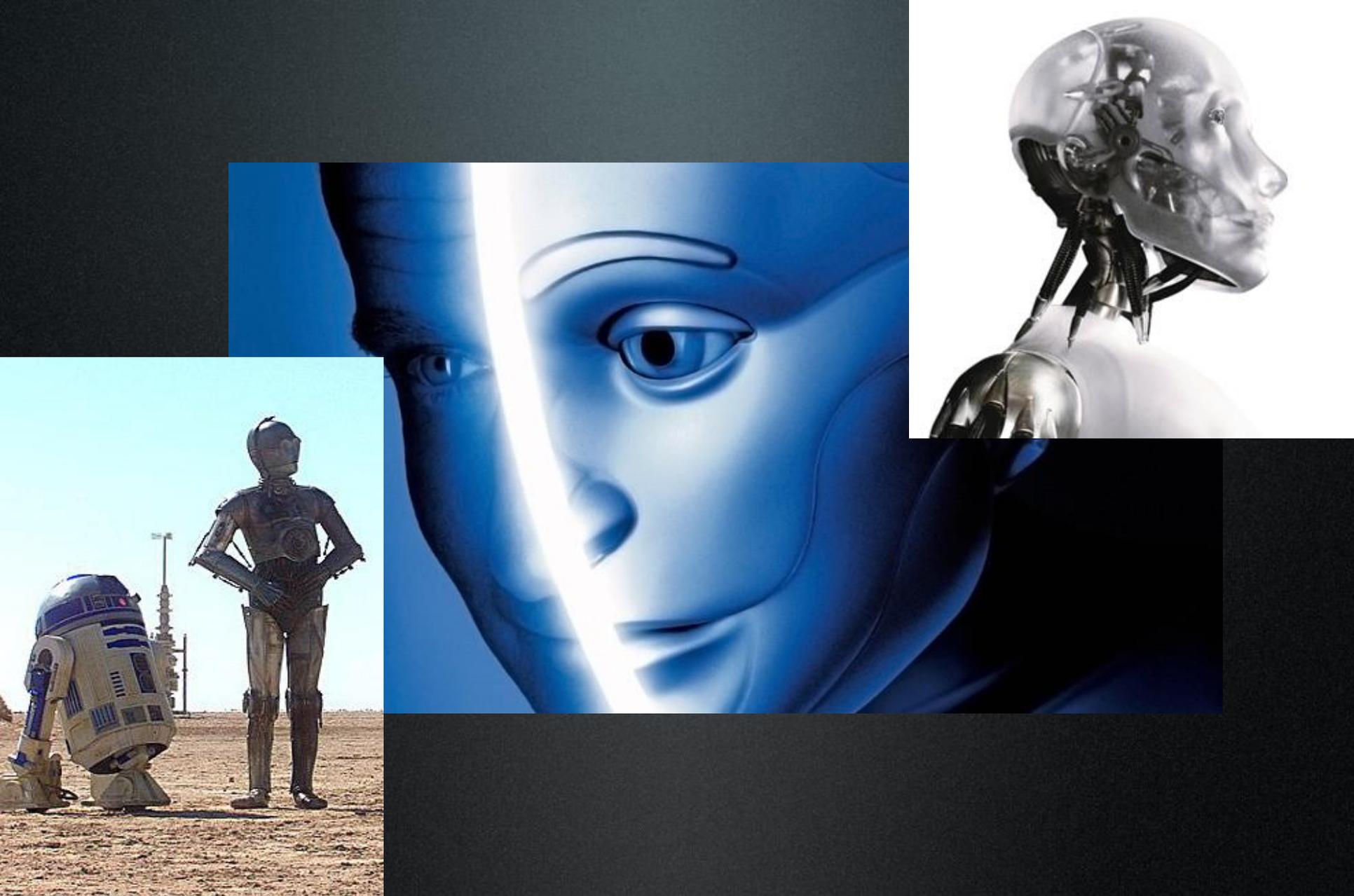


SAPHARI

SAFE AND AUTONOMOUS PHYSICAL HUMAN-AWARE ROBOT INTERACTION



ISTITUTO ITALIANO
DI TECNOLOGIA



Robotics |



Robotics | Dream & Reality



Robotics | Dream & Reality

challenges:

- H-R Interaction
- safety for Humans
- safety for Robots
- energy efficiency
- dealing with unstructured environments
- ...



toward solution:

soft
robotics



qrobotics | dreaming it possible

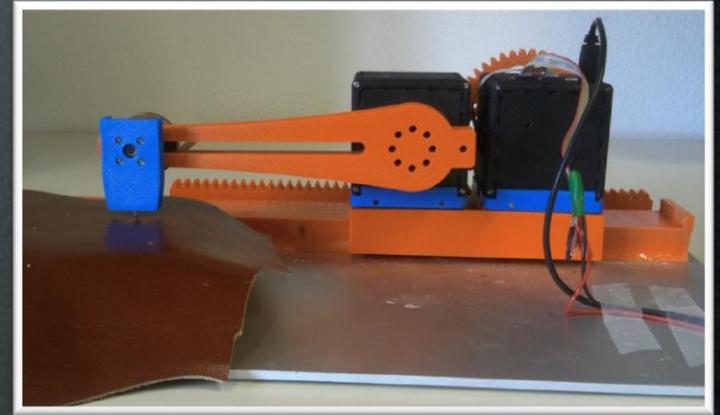
qbmove



- The Natural Motion™ actuator (VSA) you can download and build yourself
- **Three** versions (completely Open SW/HW):
 - Maker, Maker-pro, Advanced
- Easy control interface:
 - Use like a servomotor
 - Control mechanical **equilibrium position** and **stiffness**
 - Seamless integration in **C, Simulink, ROS**
- On-board sensors **read, control** and **transmit** internal configuration data and position of the output shaft

qbmove: faster than you'd think

- Elasticity in an actuator can be used to increase the dynamic range of the actuator output – in this example, to repeatedly punch and cut a leather sheet
- The application (cutting a thick leather sheet) call for higher velocities than the motor could provide
- Here we fix inertia and stiffness value, and shape the equilibrium point input to oscillate the blade at resonant frequency





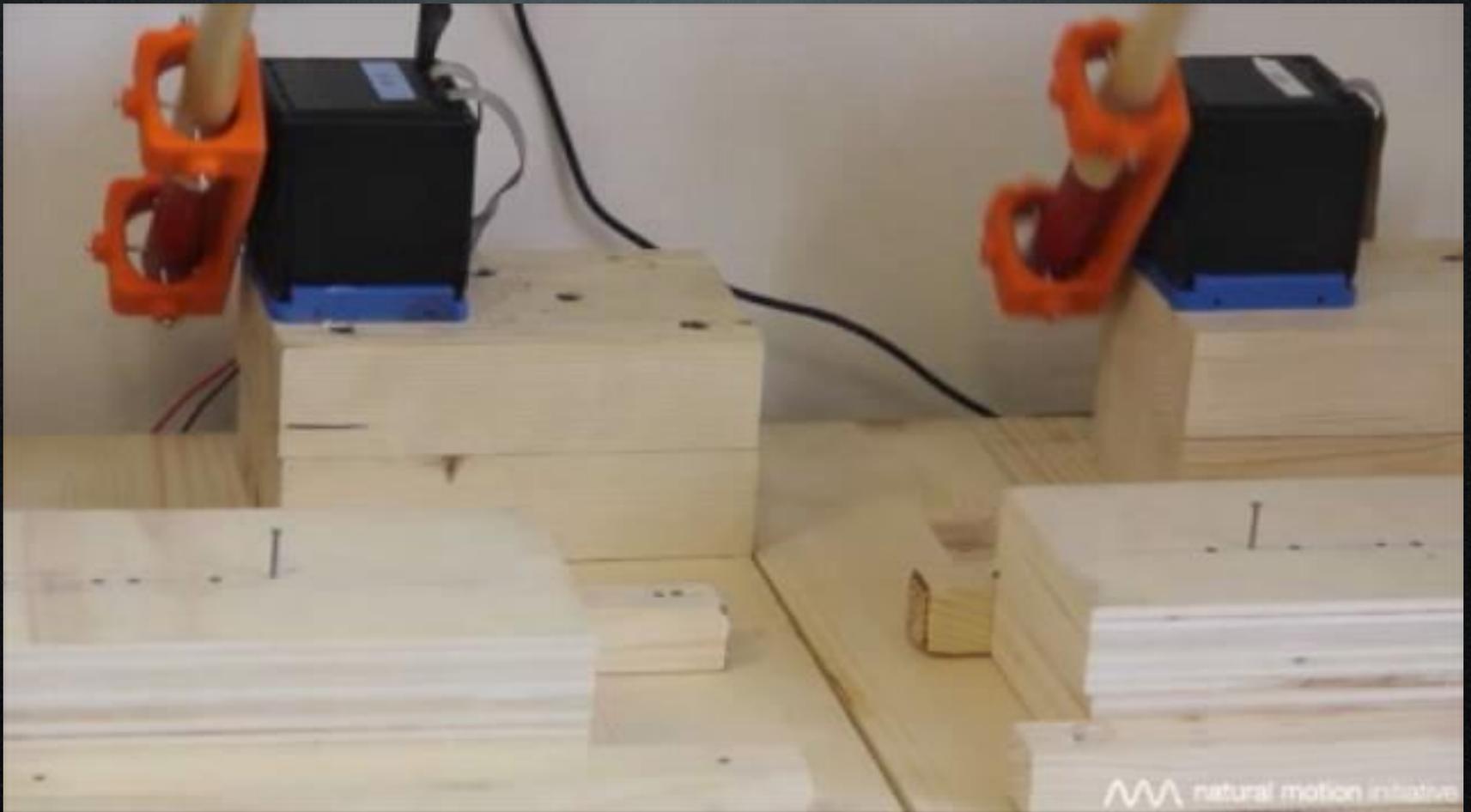
qbmove hammer: strong & robust

People are not stiff
while hammering a nail:

- reduce the musculoskeletal stress
- allow tool velocity to increase beyond that of voluntary movements
- use energy storage and release to increase efficiency



qbmove hammer: strong & robust



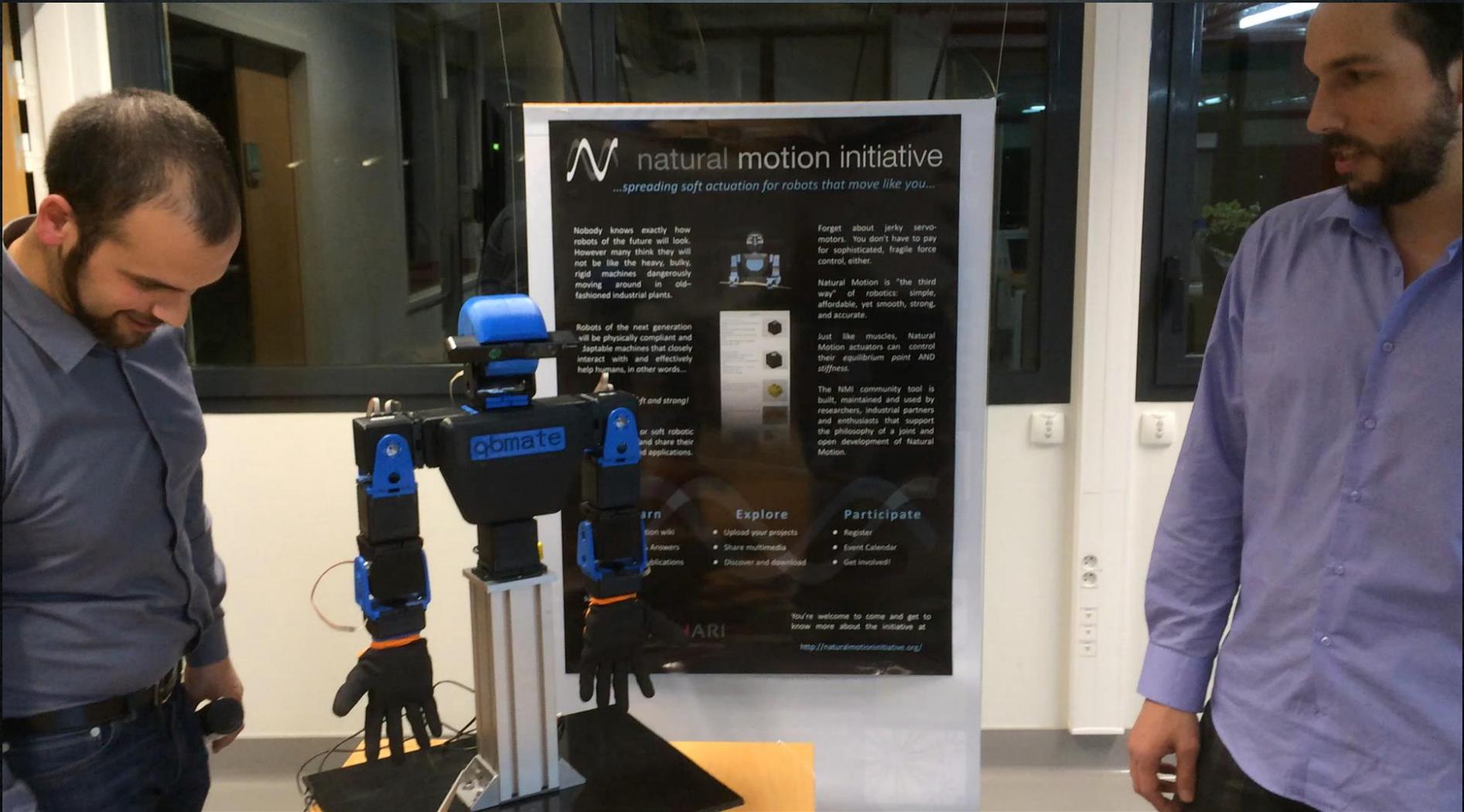
qbmoves are building blocks

- *qbmoves* are modular and easy to combine
- can be combined to build *qbmates*:
imagination is the limit!

Examples:

- a *qbmate* snake
- ...hexapod
- ...biped
- ...or torso





natural motion initiative

...spreading soft actuation for robots that move like you...

Nobody knows exactly how robots of the future will look. However many think they will not be like the heavy, bulky, rigid machines dangerously moving around in old-fashioned industrial plants.



Forget about jerky servomotors. You don't have to pay for sophisticated, fragile force control, either.

Natural Motion is "the third way" of robotics: simple, affordable, yet smooth, strong, and accurate.

Just like muscles, Natural Motion actuators can control their equilibrium point AND stiffness.

The NMI community tool is built, maintained and used by researchers, industrial partners and enthusiasts that support the philosophy of a joint and open development of Natural Motion.

Robots of the next generation will be physically compliant and adaptable machines that closely interact with and effectively help humans, in other words...

...soft and strong!

...soft robotic and share their applications.

Learn

- Join wiki
- Answers
- Publications

Explore

- Upload your projects
- Share multimedia
- Discover and download

Participate

- Register
- Event Calendar
- Get involved!



You're welcome to come and get to know more about the initiative at

<http://naturalmotioninitiative.org/>

qbmove & *qbmate*

- development is promoted by the European project



www.saphari.eu

- all design (hardware, electronics, software, etc..) are **open** and **free** to download and replicate from:



www.naturalmotioninitiative.com

- **ready-made** *qbmove* units and *qbmate* kits from:

qbrobotics

www.qbrobotics.com

qbmove

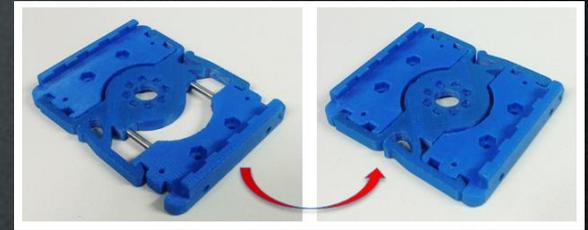
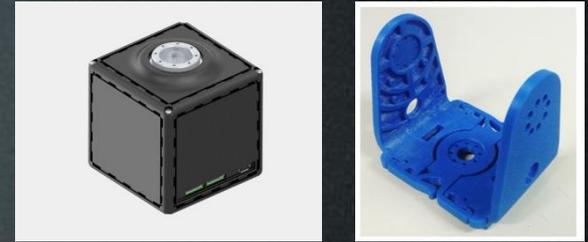
- Maker
- Maker-pro
- Advanced



QB Move	Standard	Developer*	Availability
QB Move Maker	640 €	400 €	Order Now
QB Move Maker Pro	960 €	600 €	Order Now
QB Move Advanced	1600 €	1000 €	Early 2014

qbmate

- Starter kit
- Full kit
- Advanced kit



Kit	Standard	Developer*	Avaiability
QB Mate Starter Kit	6400 €	4000 €	Order Now
QB Mate Full Kit	12800 €	8000 €	Early 2014
QB Mate Advanced Kit	19200 €	12000 €	Early 2014

robotics research institutes



\$873M/year



\$55M/year



\$4.7M/year



competition teams	research institutes	total
23.3M€	17.6M€	40.9M€ / year



\$26.9M/year



founded in 2005
100+ employees
€100M+ of investments



\$ 9.526 billion/year



\$147.4M/year

Break even point

- Our analysis gives a 120K€ BEP on a 3Y projection
- Corresponds (roughly) to 0,3% of a market volume of 40M€
- At the present stage, most of it covered with our current SAPHARI-related commission

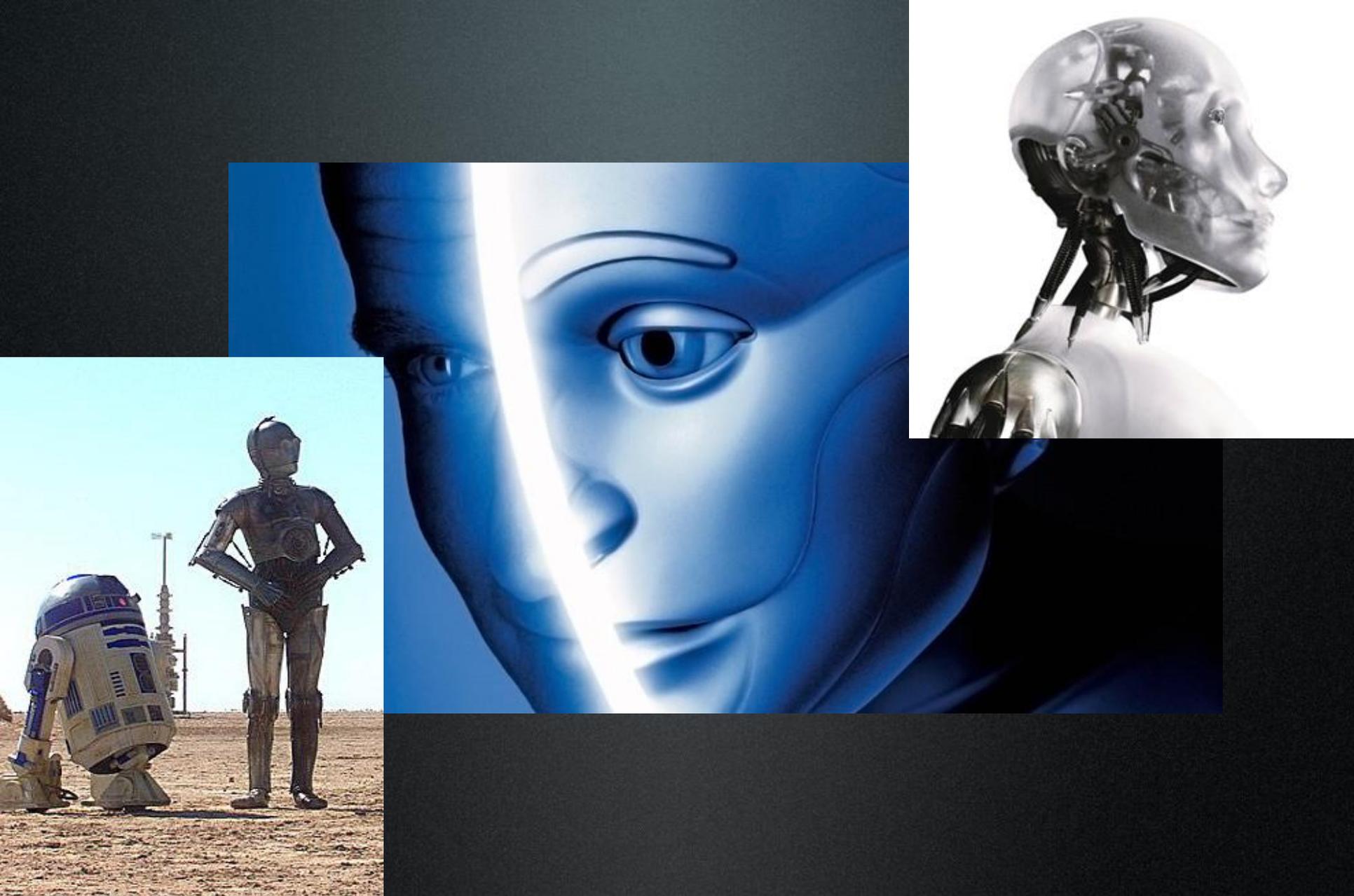
But... is this all?

...of course not!

Fixed Operating Costs	56.915
Deprecations	2.551
Total Fixed Costs	59.466
<hr/>	
Gross Revenue	162.266
Cost of Sales	82.071
Gross Margin	80.195
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Breakeven Sales level	120.323



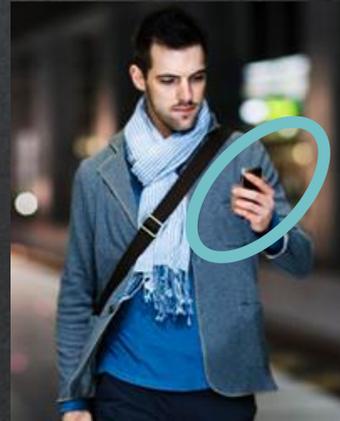
LOOK AT THE FULL LANDSCAPE



Robotics |

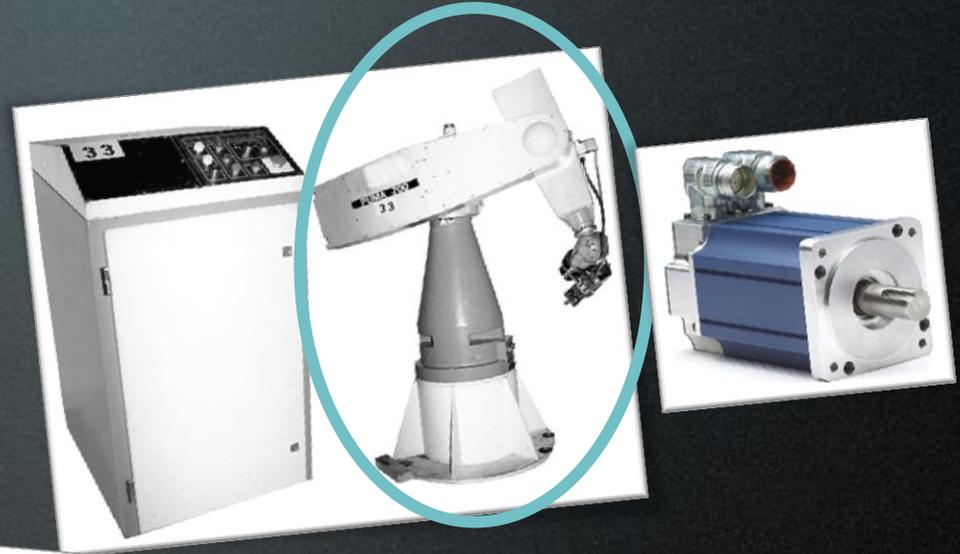
Robot Intelligence

- Yesterday: Puma
 - Motorola 68K
 - 8 MHz
 - 160 Kflops
- Today: smartphones
 - Snapdragon S4
 - 1.5 GHz
 - 6.4 Gflops

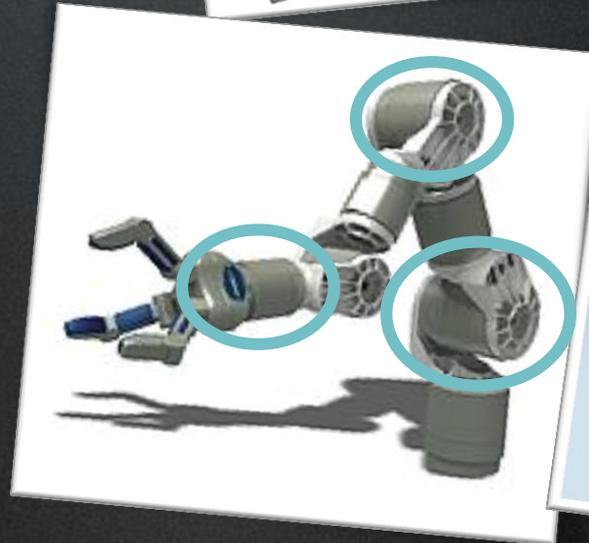


Robot Motion

- 1960's robotics
 - Unimate Puma
 - Servomotors



- 2010's robotics
 - Servomotors

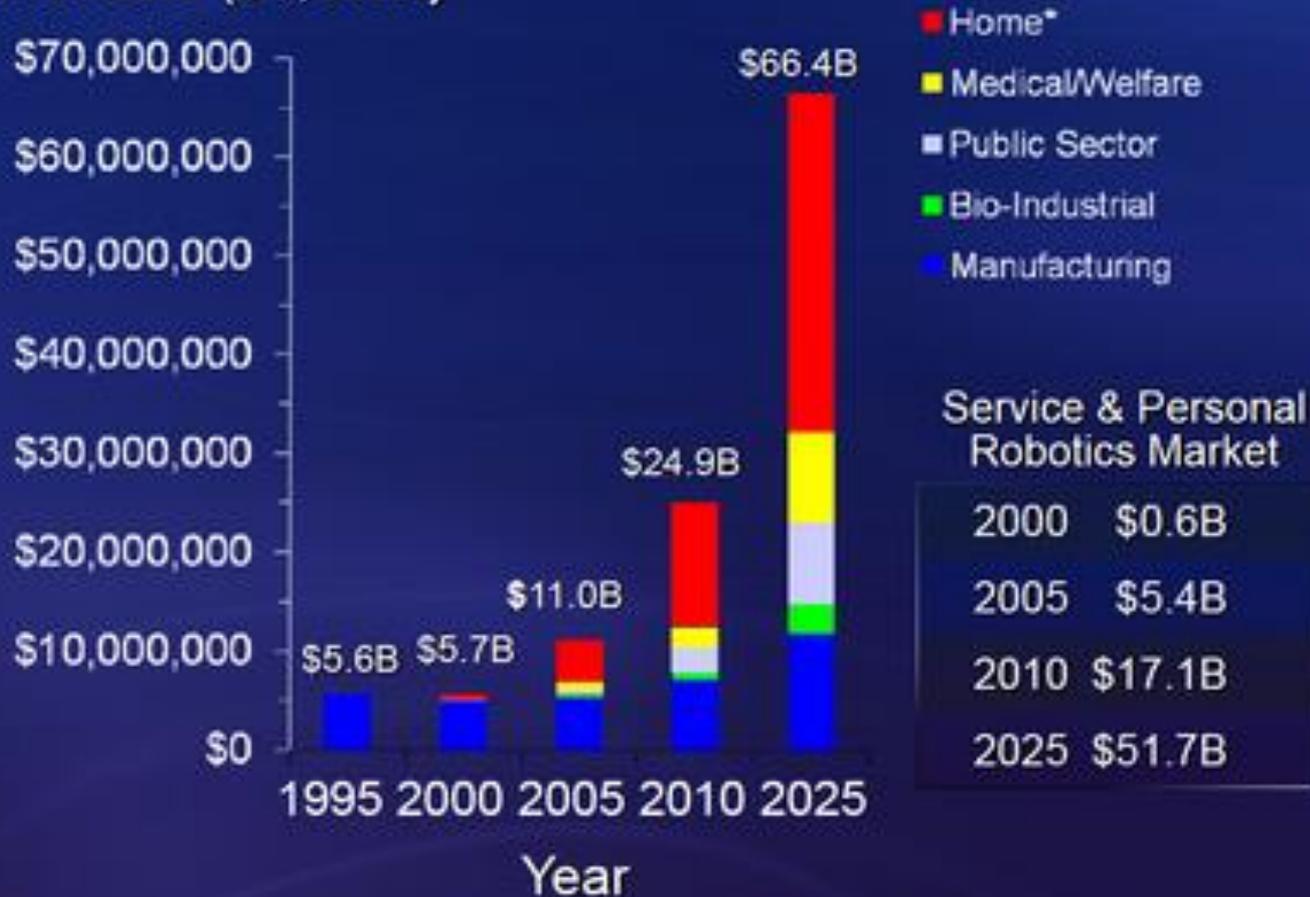


True Goal of qbrobotics

- To bring the advantages of natural motion in the light of the sun
- Natural motion technology will lead to a new generation of high-performance, adaptable and flexible **manufacturing** robots
- ... and will pave the way to **service robotics**
- **Natural motion** is going to be the **next paradigm** shift in robotics
- Our freshly granted **patent** (EU, soon US) covers **natural motion servomotors**

Mid and long term goals

Market Size (\$1,000s)



Source: Japan Robotics Association

* Excludes Low Level Electronic Toys

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